

A Novel Integrated Machine Learning Approach Utilizing Radar and Satellite Imagery for Selective Logging Remote Sensing Detection and Accompanying AI-Logging Map-Generating Webtool



Background

USAID estimates illegal logging to be a **\$150 billion** industry, destroying the world's forests. More than half of all tropical deforestation is illegal, and contributes to the **1.5 gigatons of carbon** released from deforestation annually (WWF). However, developing countries struggle **without the funding or human resources** to monitor their vast expanse of forests through forest patrol. The advent of machine learning allows for a remote sensing solution able to monitor the large region of forestry at low costs. At the mass quantities of selective logging occurring, forests are left with **significant reductions in tropical biomass**, growth of **weeds/ poor quality - low diversity trees**, **loss in biodiversity**, and are more susceptible to **forest fires and soil erosion**.

Selective Logging



Image Credited To Tahreer Photography / Getty Images

Clear Cut Logging



Image Credited To Mongabay Photos by Rhett A. Butler

In the world's humid tropics, home to vast majority of forestry, **persistent cloud cover** often hinders the acquisition of clear optical satellite imagery. However, **radar imagery** overcomes this limitation by penetrating cloud cover, presenting an untapped opportunity for monitoring these regions.



Image Credited To DrivenData

Nearly 50-90% of tropical timber is illegally logged

Illegal logging is estimated to be a \$150 billion industry

1.5 gigatons of carbon result annually from deforestation

Research Question

How can an **integration of optical satellite and radar (SAR)** sensory data be used to improve logging detection models performance and accuracy in classifying **selective logging** and in addition create a interactive tool for forest protection agencies to identify logging occurrences?

Data Acquisition

Sentinel 1 and 2 imagery was obtained through Google Earth Engine. In addition, to classify data points as logged / stable, the open source GFC annual forest map was used. The dataset selected **location as Jamari National Park**, which has sustainable forest management practice (**selective logging**) permits yearly.



Data Location



The data sets comprised the following **12 band values** from **Sentinel 1** and **Sentinel 2**. Sentinel: VH and VV bands Sentinel 2: B2, B3, B4, B5, B6, B7, B8, B8A, B11, and B12 bands for both Jan/Dec. In all, **24 band values** were used for the combined Sentinel 1 and Sentinel 2 data set.

Selected Sentinel 2 Bands

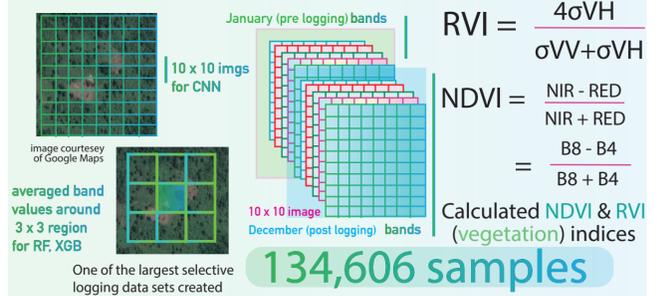
Sentinel 2 Feature	Resolution	Wavelength	Description
B2	10m	443.9nm (S2A) / 412.3nm (S2B)	Blue
B3	10m	490.6nm (S2A) / 492.1nm (S2B)	Green
B4	10m	560nm (S2A) / 559nm (S2B)	Red
B5	20m	664.5nm (S2A) / 665nm (S2B)	Red Edge 1
B6	20m	703.9nm (S2A) / 703.8nm (S2B)	Red Edge 2
B7	20m	740.2nm (S2A) / 739.1nm (S2B)	Red Edge 3
B8	10m	782.5nm (S2A) / 779.7nm (S2B)	NIR(Near Infrared)
B8A	20m	835.1nm (S2A) / 833nm (S2B)	Red Edge 4
B11	20m	864.8nm (S2A) / 864nm (S2B)	SWIR 1
B12	20m	945nm (S2A) / 943.2nm (S2B)	SWIR 2

Selected Sentinel 1 Bands

Sentinel 1 Feature	Resolution
VH	10m
VV	10m

Data Processing

Using **GFC map** as reference, **logged pixels** and a **subset of the stable forest pixels** were identified to create a **balanced dataset** for unbiased model. For RF/XGB, averaged values of all bands were taken around a **3x3 region**. For the CNN, raw **10x10 images** were used. The December and January bands were then merged for model to learn the difference in band values before/after logging. For the combined Sentinel 1/2 dataset, the **Sentinel 1 + 2 imagery was merged through concatenation**.

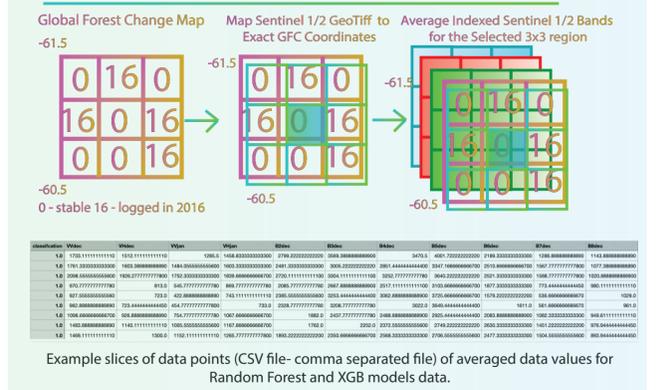


$$RVI = \frac{4\sigma VH}{\sigma VV + \sigma VH}$$

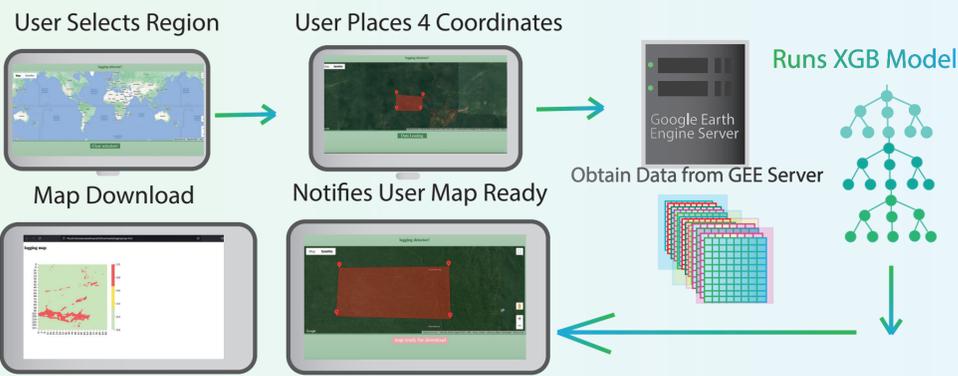
$$NDVI = \frac{NIR - RED}{NIR + RED} = \frac{B8 - B4}{B8 + B4}$$

Calculated NDVI & RVI (vegetation) indices

134,606 samples



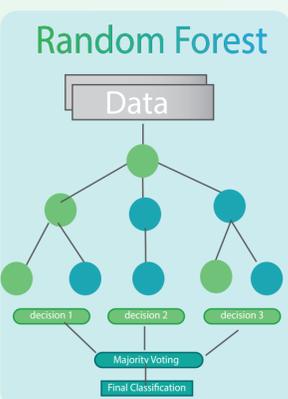
Logging Detector Webtool



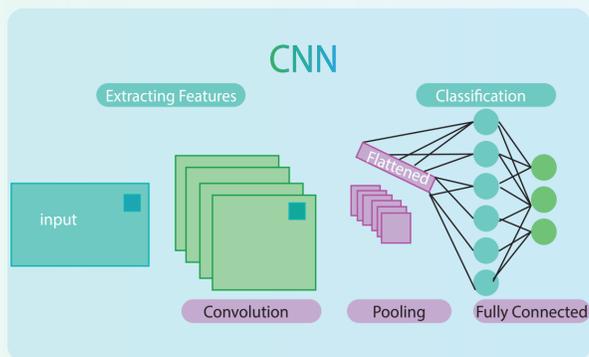
Models

The various models explored are CNN (U- Net), Random Forest, Gradient Boosted Trees. The models are built using python libraries and trained and tested on the Sentinel 1, Sentinel 2, and Sentinel 1 and 2 datasets.

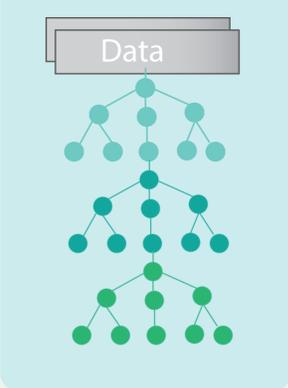
Machine Learning



Deep Learning

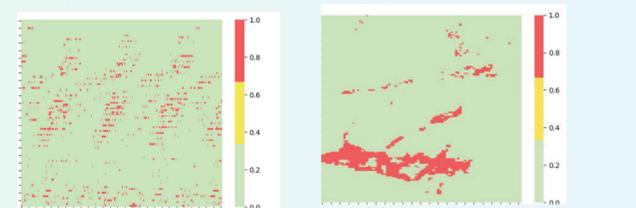


Gradient Boost



Data Inputted -> 3 models run -> Map Output

Logging Maps



Small regions were selected for use as testing locations for **logged/stable forest prediction maps**. Using MATLAB and seaborn libraries, the models will be used to **output prediction for each pixel** and generate the maps shown above.

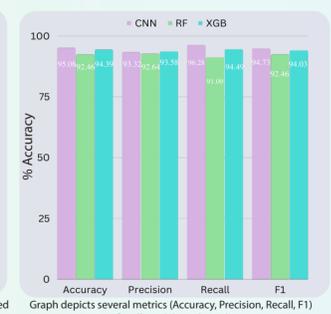
Results

The models all improved from the integration of radar and satellite imagery, with the CNN performing best at **95.08 % accuracy** and **94.73 F1**. Pre existing solutions record **88% accuracy rate** using only Sentinel 1, so this is a **7.08% increase**.

Accuracy With/ Without Sentinel 1/2 Integration



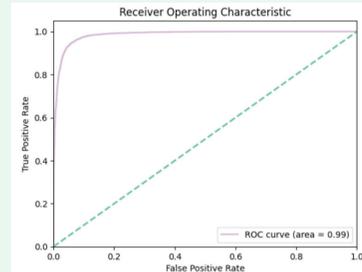
All Models on Integrated Data Set



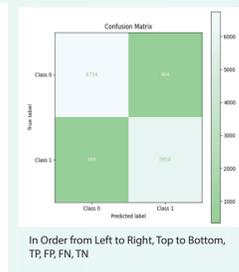
Accuracy Increase From Integration



AUROC



Confusion Matrix



Metrics

TP = True positives, i.e. the number of deforested areas classified as deforested.
 TN = True negatives, i.e. the number of forested areas classified as forested.
 FP = False positives, i.e. the number of forested areas classified as deforested.
 FN = False negatives, i.e. the number of deforested areas classified as forested

Accuracy = (TP + TN) / (TP + TN + FP + FN)
 Precision = TP / (TP + FP)
 Recall = TP / (TP + FN)
 F1 = 2 x (Precision x Recall) / (Precision + Recall)

Future Work

- 1 Reach out to **forest protection agencies** for feedback and testing of the web tool to make improvements and demonstrate functionality by contacting **Amazon Trust, Rainforest Watch, and Rainforest Action Network**.
- 2 Future Work includes hosting the website as a **live website** for anyone to access and use (currently limited by need for funding for cloud storage/Google Earth Engine API calls).
- 3 Contact **Brazilian Forest Service** for access to logging records and build training data classifications on more accurate logging records rather than Global Forest Cover Map

Significance

- 1 **Integrating** both optical and radar imagery for deforestation classification results in **massive performance improvements** (CNN - 3.13%) and **7.08% increase** from existing models
- 2 Created a novel tool able to be used worldwide to detect logging occurrences
- 3 Models applicability extends beyond training location to worldwide

All images/graphs were created by the student researcher unless otherwise noted.